

Chinook

function gripper, inspection ROV built by SEAMOR Marine with the capability of working to depths of 300 meters (1,000 ft). Its compact profile allows for ease of use with minimal crew and mobilization onto smaller vessels of opportunity.

- instrumentation

Coastal and Inland Infrastructure Accident and Forensic Investigations Route & As-built Surveys Photographic & Video Documentation Biological & Oceanographic Sampling Green Energy Infrastructure Offshore Wind Wave Energy High resolution forward inspection camera, and rear-facing fixed camera Basic manipulator functionality for sea floor object recovery Skid attachment for quick fitting of a variety of tooling and



General

Max. Op. Depth 300 m (1,000 ft)

Size (L x W x H) 686mm x 384mm x 406mm

(27 " x 15.1 " x 16 ")

Weight in Air 33 kg (72 lbs)

Construction Anodized aluminum, stainless

steel, syntactic foam and marine

grade polymers

Speed 2 knots

Vehicle Description

Thrusters 4 x Lateral

2 x Vertical

Cameras NTSC or PAL (full broadcast-quality)

3x optical, up to 32x total zoom

Lighting Two (2) x 1,500 lumens (3,000 lumens total)

Dimmable; 90-degree rotation

Aux Lighting Two (2) x 1,500 lumens (3,000 lumens total)

Tether Length 335 m (1,100 ft) x Dia.10 mm (0.4 ")

Breaking Strength 700 kgf, Kevlar reinforced

Sensors Pressure/Depth

Compass Heading

Pitch and Roll

Dedicated leak and temperature sensors in both

the electronics and camera canisters

Control System Pelican case mounted controller

Built-in 15 " LCD monitor

Digital video recorder

Video overlay: depth, heading, auto-depth, auto-heading, pitch/roll, tether turns counter, date &

time

Operates on standard 120 volt power

Optional Equipment

CT/UT Probe Integration; Cutter; Various

Scanning Sonars

Replacement port propeller

Replacement starboard propeller

Phoenix International Holdings, Inc.
An employee owned company

